

晶采光電科技股份有限公司 AMPIRE CO., LTD.

SPECIFICATIONS FOR LCD MODULE

CUSTOMER	
CUSTOMER PART NO.	
AMPIRE PART NO.	AM-1280800WVTZQW-T83H
APPROVED BY	
DATE	

- ☐ Preliminary Specification
- **■** Formal Specification

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Approved by	Checked by	Organized by
Patrick	Kokai	Mark

^{*}This specification is subject to change without notice.

RECORD OF REVISION

Revision Date	Page	Contents	Editor
2022/04/25		New Release	Mark

1.0 General Descriptions

1.1 Introduction

The LCM is a color active matrix thin film transistor (TFT) liquid crystal display (LCD) that uses amorphous silicon TFT as a switching device. It is composed of a TFT LCD panel, a backlight system, column driver and row driver circuit. This TFT LCD has a 10.1-inch diagonally measured active display area with WXGA resolution (1280 horizontal by 800 vertical pixels array).

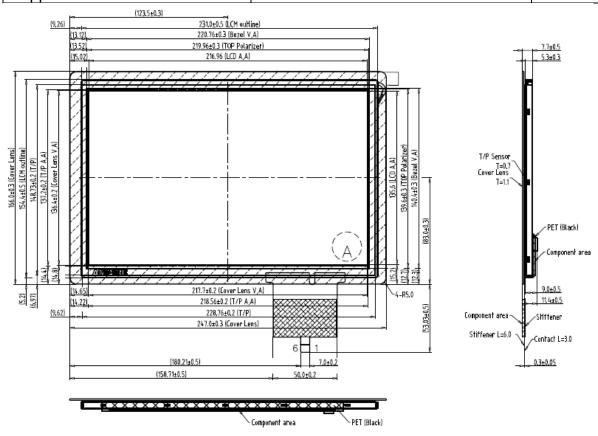
1.2 Features

- 10.1" TFT LCD Panel
- LED Backlight System
- Supported WXGA 1280x800 pixels resolution
- Compatible with RoHS Standard
- Build in LED Driver
- Touch Panel:

- · Controller: ILI2511
- Interface: I2C
- · Cover Glass: T=1.0mm, black frame.

1.3 Product Summary

Items	Specifications	Unit
Screen Diagonal	10.1	Inch
Active Area	216.96(H) x 135.6(V)	mm
Pixel Format	1280(RGB) x800	-
Pixel Pitch	0.1695(H) x 0.1695 (V)	mm
Pixel Arrangement	R.G.B. Vertical Stripe	-
Display Mode	Normally Black	-
White Luminance	850 (Typ.)	cd /m2
Contrast Ratio	800 : 1 (Typ.)	-
Response Time	25	msec
Input Voltage	3.3	V
Electrical Interface (Logic)	LVDS	-
Support Color	16.7M	-



2.0 Absolute Maximum Ratings

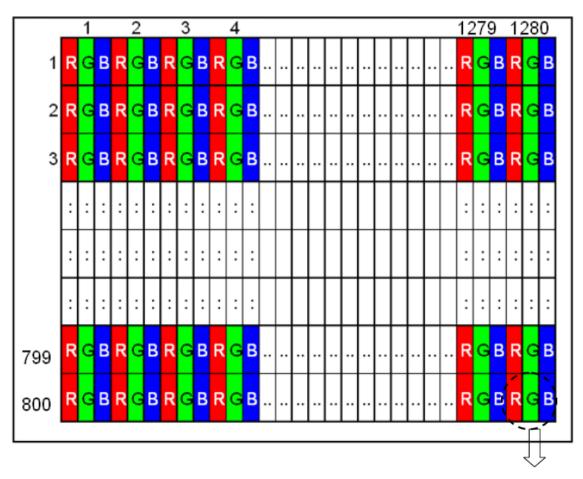
ITEM	SYMBO	VALU	JES	UNIT	REMARK	
I I CIVI	L	MIN	MIN MAX		KEWAKK	
Power Voltage	V_{DD}	-0.3	4.0	V	VSS=0V, TA=25℃	
1 ower voitage	V_{LED}	-0.3	24	V		
Operation Temperature	T_{op}	-20	70	$^{\circ}$ C		
Storage Temperature	T _{st}	-30	80	$^{\circ}\!\mathbb{C}$		

Note 1: The absolute maximum rating values of this product are not allowed to be exceeded at any times. Should a module be used with any of the absolute maximum ratings exceeded, the characteristics of the module may not be recovered, or in an extreme case, the module may be permanently destroyed.

3.0 Pixel Format Image

Figure 2 shows the relationship of the input signals and LCD pixel format image.

Figure 2 Pixel Format



R+G+B dots=1 pixel

4.0 Optical Characteristics

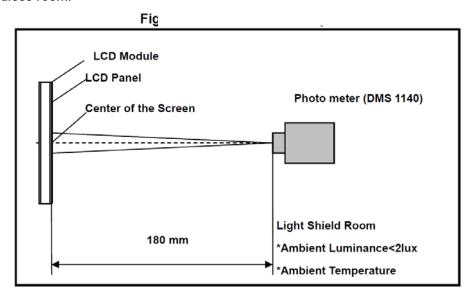
The optical characteristics are measured under stable conditions as following notes

Table 2 Optical Characteristics

Item	Conditions		Min.	Тур.	Max.	Unit	Note	
Viewing Angle	Horizontal	θ∟	(75)	(85)	-			
		θR	(75)	(85)	-	degree	(1),(2),(3)	
(CR>10)	Vertical	θт	(75)	(85)	-	3	(//(//(-/	
	Vertical	θв	(75)	(85)	-			
Contrast Ratio	Center		(600)	(800)	-	-	(1),(2),(4)	
Response Time	Rising		-	-	-	ms		
	Falling		-	-	-	ms	(1),(2),(5)	
	Rising + Fallin	g	-	25	-	ms		
	NTSC		-	45	-	%	(1),(2)	
	Red	Χ		0.561		-	(1),(2)	
	Red	у		0.334		-		
Color	Green	Χ		0.341		-		
Chromaticity	Green	у	Тур.	0.568	Тур.	-		
(CIE1931)	Blue	Χ	-0.05	0.161	+0.05	-	(1),(2)	
	Blue	у		0.129		-		
	White	Χ		0.313		-		
	White	у		0.329		-		
White Luminance	Center		680	850	-	cd/m^2	(1),(2),(6)	
Luminance Uniformity	9Points		70	75	-	%	(1),(2),(6)	

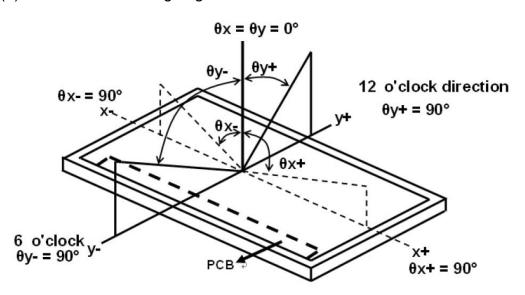
Note(1) Measurement Setup:

The LCD module should be stabilized at given temperature(25°C) for 15 minutes to Avoid abrupt temperature change during measuring. In order to stabilize the luminance, the measurement should be executed after lighting backlight for 15 minutes in a windless room.



Note(2) The LED input parameter setting as: PWM: duty 100 %

Note(3) Definition of viewing angle:



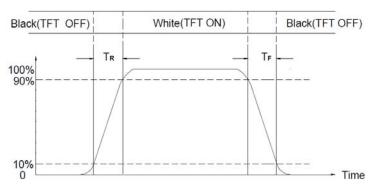
Note(4) Definition of Contrast Ratio (CR)

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The contrast ratio can be calculated by the following expression Contrast Ratio (CR) = L255 / L0

L63: Luminance of gray level 255, L0: Luminance of gray level 0

Note(5) Definition of Response Time (TR, TF)



Note(6) Definition of brightness luminance

Active area is divided into 9 measuring areas (Refer to bellow figure). Every measuring point is placed at the center of each measuring area.

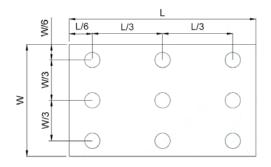
Bmin

Luminance Uniformity (Yu) = _____

Bmax

L ---- Active area length

W ---- Active area width



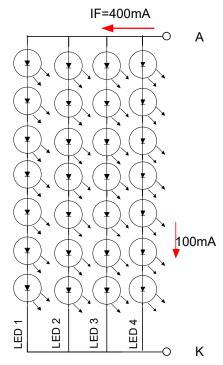
Bmax: The measured maximum luminance of all measurement position.

Bmin: The measured minimum luminance of all measurement position.

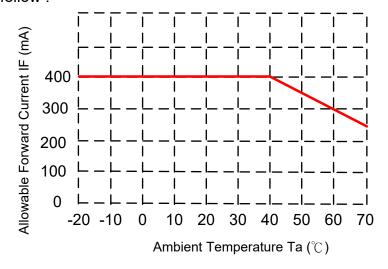
5.0 Backlight Characteristics

ITEM	SYMBOL	MIN	TYP	MAX	UNIT	CONDITION
LED Backlight Voltage	V_{BL}		21	23.1	V	For reference
LED Backlight Current	I_{BL}	-	400	-	mA	Ta=25℃
LED Life Time			50K	1	KHr	Note*

Note*: Brightness to be decreased to 50% of the initial value.



When LCM is operated over 40 $^{\circ}\text{C}^{}$ ambient temperature, the ILED should be follow :



6.0 Electrical Characteristics

6.1 TFT LCD Module Interface Connector

Table 4 Connector Name / Designation

	_
Item	Description
Manufacturer / Part Number	Starconn / 300E40-0010RA-G3
Mating Model Number	TBD or compatible

Table 5 Signal Pin Assignment

Pin#	Signal Name	Description	Remarks
1	NC	Not Connect	-
2	VDD	Power Supply, 3.3V (typical)	-
3	VDD	Power Supply, 3.3V (typical)	
4	VDD_EDID	Power Supply for EDID I2C Flash IC	
5	SCL_EDID	I2C Serial Clock for EDID I2C Flash IC	
6	SDA_EDID	I2C Serial Data for EDID I2C Flash IC	
7	NC	Not Connect	
8	LV0N	-LVDS differential data input	
9	LV0P	+LVDS differential data input	
10	GND	Ground	
11	LV1N	-LVDS differential data input	
12	LV1P	+LVDS differential data input	
13	GND	Ground	
14	LV2N	-LVDS differential data input	
15	LV2P	+LVDS differential data input	
16	GND	Ground	
17	LVCLKN	-LVDS differential data input	
18	LVCLKP	+LVDS differential data input	
19	GND	Ground	
20	LV3N	-LVDS differential data input	
21	LV3P	+LVDS differential data input	
22	GND	Ground	
23	LED_GND	Ground for LED Driving	
24	LED_GND	Ground for LED Driving	
25	LED_GND	Ground for LED Driving	
26	NC	Not Connect	
27	LED_PWM	PWM Input signal for LED driver :3.3V	
28	LED_EN	LED Enable Pin :3.3V	
29	NC	Not Connect	
30	NC	Not Connect	
31	LED_VCC	Power Supply for LED Driver :12V	
32	LED_VCC	Power Supply for LED Driver :12V	
33	LED_VCC	Power Supply for LED Driver :12V	
34	NC	Not Connect	
35	BIST	BIST pin. (Keep NC or High if not use.)	
36	CSB	Serial communication enables. (For test only)	
37	SCL	Serial communication clock input (For test only)	
38	SDA	Serial communication data input. (For test only)	
39	SCL_I2C	Serial communication clock input. (For test only)	
40	SDA_I2C	Serial communication data input. (For test only)	

Note: All input signals shall be low or Hi-resistance state when VDD is off.

6.2 LVDS Receiver

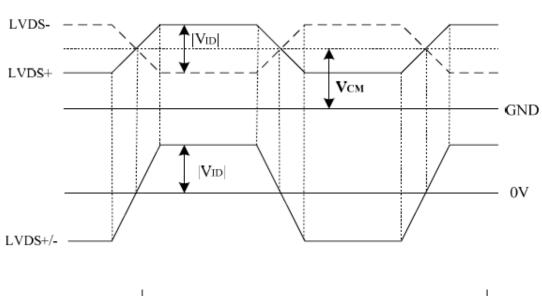
6.2.1 Signal Electrical Characteristics For LVDS Receiver

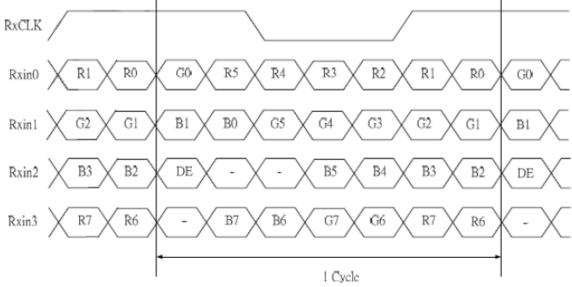
Table 7 LVDS Receiver Electrical Characteristics

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
Differential Input High	∨th	-	-	+100	mV	V _{CM} =+1.2V
Differential Input Low	VtI	-100	-	-	mV	V _{CM} =+1.2V
Magnitude Differential Input	V _{ID}	200	-	400	mV	-
Common Mode Voltage	V _{CM}	0.3+ (VID/2)	-	VDD-1.2-(VID/2)	٧	-
Common Mode Voltage	ΔV_{CM}	-	-	50	m∨	V _{CM} =+1.2V

Note (1) Input signals shall be low or Hi-Z state when VDD is off.

(2) All electrical characteristics for LVDS signal are defined and shall be measured at the interface connector of LCD.





7.0 Interface Timings

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7.1 Timing Characteristics

Interface Timings

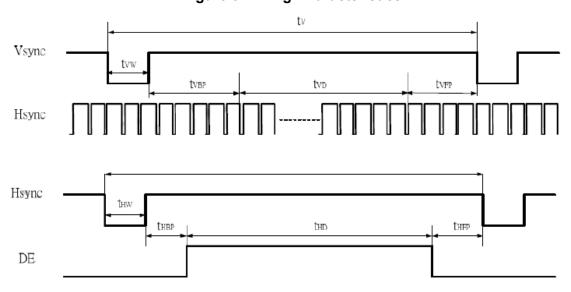
Symbol	Min.	Тур.	Max.	Unit
Fclk	(70.0)	(72.4)	(76.6)	MHz
HT	(1,410)	(1,440)	(1,470)	Clocks
HA		1,280		Clocks
VT	(828)	(838)	(868)	Lines
VA		800		Lines
FV	-	(60)	-	Hz
	Fclk HT HA VT VA	Symbol Min. Fclk (70.0) HT (1,410) HA VT (828) VA VA	Symbol Min. Typ. Fclk (70.0) (72.4) HT (1,410) (1,440) HA 1,280 VT (828) (838) VA 800	Symbol Min. Typ. Max. Fclk (70.0) (72.4) (76.6) HT (1,410) (1,440) (1,470) HA 1,280 VT (828) (838) (868) VA 800

Note1: HT * VT *Frame Frequency≤(76.6) MHz

Note2: All reliabilities are specified for timing specification based on refresh rate of 60Hz.

7.2 Timing Diagram of Interface Signal (DE mode)

Figure 8 Timing Characteristics



8.0 Power Consumption

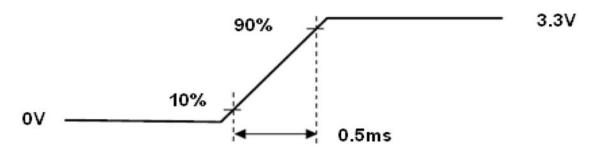
Input power specifications are as follows.

Table 8 Power Consumption

Item		Symbol	Min	Тур.	Max	Unit	Note
LCD Drive Voltage		VDD	3.0	3.3	3.6	V	(2),(4)
VDD Current	White Pattern	IDD	-1	0.27		Α	(3),(4)
VDD Power Consumption	White Pattern	PDD			1.0	W	(3),(4)
Rush Current		Irush			1.5	А	(1),(4),(5)
Allowable Logic/LCD Drive Ripple Voltage		VDDrp			300	mV	(4)
LED Driver Power Voltage		VLED		12		V	
LED Driver Current		ILED	I	0.75	1	А	LED_EN =ADJ=High
ADJ frequency		f _{PWM}	100	I	20k	Hz	
ADJ logic level High		VIH	2.4			V	
ADJ logic level Hig	h	VIL			0.7	V	

Note (1) Measure Condition

Figure 9 VDD rising time



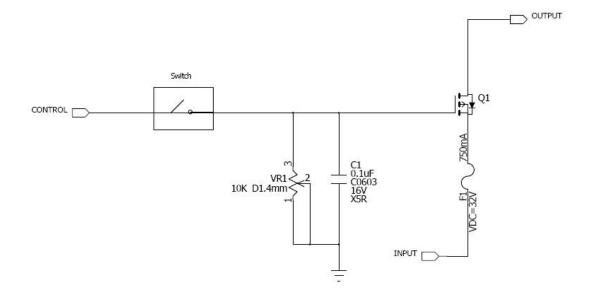
VDD rising time

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Note (2) Frame Rate=60Hz, VDD=3.3V,DC Current.

Note (3) Operating temperature 25°C , humidity 55%RH.

Note (4) The reference measurement circuit of rush current.



9.0 Power ON/OFF Sequence

ΕN

Power on/off sequence is as follows. Interface signals are also shown in the chart. Signals from any system shall be Hi-Z state or low level when VDD is off.

Figure 11 Power Sequence

Table 9 Power Sequencing Requirements

Parameter	Symbol	Unit	Min	Тур.	Max
VIN Rise Time	T1	ms	0.5		10
VIN Good to Signal Valid	T2	ms	30		90
Signal Valid to Backlight On	T3	ms	200		
Backlight Power On Time	T4	ms	0.5		
Backlight VDD Good to System PWM On	T5	ms	10		
System PWM ON to Backlight Enable ON	T6	ms	10		
Backlight Enable Off to System PWM Off	T7	ms	0		
System PWM Off to B/L Power Disable	Т8	ms	10		
Backlight Power Off Time	Т9	ms		10	30
Backlight Off to Signal Disable	T10	ms	200		
Signal Disable to Power Down	T11	ms	0		50
VIN Fall Time	T12	ms		10	30
Power Off	T13	ms	500		

10.0 Projected capacitive-type Touch panel specification Basic Characteristic

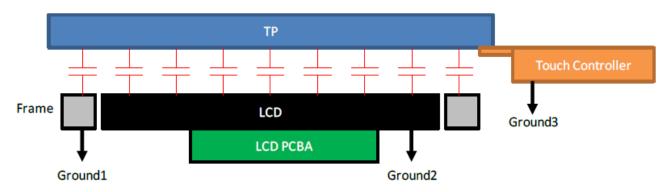
ITEM	SPECIFICATION			
Туре	Projective Capacitive Touch Panel			
Activation	Max 10-fingers or Signal-finger			
X/Y Position Reporting	Absolute Position			
Touch Force	No contact pressure required			
Calibration	No need for calibration			
Report Rate	Approx 80 points/sec			
Interface	I2C			
Control IC	ILI2511			

Item	Symbol	Min.	Тур.	Max.	Unit
Power Supply Voltage	VIN	3.14	3.3	3.46	٧
Low Level Input Voltage	VIL	0		0.3*VIN	V
High Level Input Voltage	VIH	0.6*VIN		VIN	V

10.2 Interface

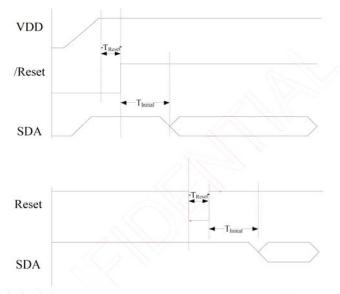
Pin No.	Symbol	Function				
1	VIN	Power Supply for TP controller				
2	SCL	I2C Data				
3	SDA	I2C Clock				
4	INT	Interrupt Request pin				
5	RES	Rest pin to Master Chip				
6	GND	GND				

TP needs to work in environment with stable stray capacitance. In order to minimize the variation in stray capacitance, all conductive mechanical parts must not be floating. Intermittent floating any conductive part around the touch sensor may cause significant stray capacitance change and abnormal touch function. It is recommended to keep all conductive parts having same electrical potential as the GND of the touch controller module.



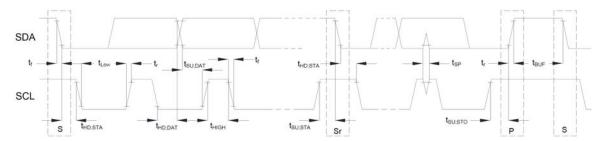
GND1, GND2 and GND3 should be connected together to have the same ground

10.3 Power- on Timing Chart (IIC interface)



Symbol	Parameter	MIN.	MAX.	Unit
T _{Initial}	After powering-on or resetting the device, the device	-	100	ms
\sim	needs I _{nitial} time to configure the system.			
T _{Reset}	/Reset pin low hold time	50	-	μs

10.4 IIC AC Waveform



10.5 IIC Characteristics

Cumbal	Parameter		100KHz	:	400KHz			
Symbol	Parameter	Min	Max	Unit	Min	Max	Unit	
f _{SCL}	SCL clock frequency	0	100	kHz	0	400	KHz	
t _{hd;sta}	Hold time (repeated) START condition. After this period, the first clock pulse is generated	4.0	-	μs	0.6	-	μs	
t _{LOW}	LOW period of the SCL clock	4.7	-	μs	1.3	-	μs	
t _{HIGH}	HIGH period of the SCL clock	4.0		μs	0.6	-	μs	
t _{su:sta}	Set-up time for a repeated START condition	4.7	-	μs	0.6	-	μs	
t _{HD:DAT}	Data hold time	0	3.45	μs	0	0.9	μs	
t _{SU;DAT}	Data set-up time	250	-	ns	100	-	ns	
t _r	Rise time of both SDA and SCL signals	-	1000	ns	-	300	ns	
t _f	Fall time of both SDA and SCL signals	-	300	ns	-	300	ns	
t _{su;sto}	Set-up time for STOP condition	4.0	-	μs	0.6	-	μs	
t _{BUF}	Bus free time between a STOP and START condition	4.7	-	μs	1.3	-	μs	

10.6 Format Protocol Protocol V3.X Command List

CMD Code	Name	Set /Get	Note	b7	b6	b5	b4	b3	b2	b1	b0
0x10	Touch	Get		0: No touch							
	Information			1: Last Report at IE	0 to ID	5 (incl	ude re	lease :	status)		
				2: Last Report at ID	6 to ID	9 (incl	ude re	lease :	status)		
			ID0	1: Touch Down,	0	V LI	ah dira	ction	coordin	ato	
				0: Touch Off	0	^_' "	gri dire		Journal	iale	\Diamond
				X_Low direction co	ordinate	,					
				0	0	Y_Hi	g h dire	ection o	coordin	ate	
				Y_Low direction co	ordinate				\		
				Touch Pressure					>		
			ID1	1: Touch Down, 0: Touch Off	0	X_Hi	g h d ire	ection o	coordin	ate	
				X_Low direction co	ordinate	7/					
				0	0	Y_Hi	gh dire	ection o	coordin	ate	
				Y_Low direction co	ordinate						
				Touch Pressure							
1	1	1			1	ı					
		,	ID2	1: Touch Down, 0: Touch Off	0	X_Hiç	gh dire	ction c	oordina	ate	
			/ \	X_Low direction co	ordinate						
	·			0	0	Y_Hiç	gh dire	ction c	oordina	ate	
				Y_Low direction co	ordinate						
				Touch Pressure							
			1D3	1: Touch Down, 0: Touch Off	0	X_Hiç	gh dire	ction c	oordina	ate	
				X_Low direction co	ordinate						
				0	0	Y_Hiç	gh dire	ction c	oordina	ate	
				Y_Low direction co	ordinate						
				Touch Pressure							
			ID4	1: Touch Down, 0: Touch Off	0	X_Hiç	gh dire	ction c	oordina	ate	
				X_Low direction co	ordinate						
				0	0	Y_Hiç	gh dire	ction c	oordina	ate	
				Y_Low direction co	ordinate						
				Touch Pressure							

			ID5	1: Touch Down,					
				0: Touch Off	0	X_High direction coordinate			
				X_Low direction co	ordinate				
				0	0	Y_High direction coordinate			
				Y_Low direction co	ordinate	;			
				Touch Pressure					
0x14	Touch Information 2	Get	ID6	1: Touch Down, 0: Touch Off	0	X_High direction coordinate			
				X_Low direction co	ordinate				
				0	0	Y_High direction coordinate			
				Y_Low direction co	ordinate				
				Touch Pressure					
			ID7	1: Touch Down,					
				0: Touch Off	0	X_High direction coordinate			
				X_Low direction co	ordinate				
				0	0	Y_High direction coordinate			
				Y_Low direction co	ordinate				
				Touch Pressure					
I						1			
			ID8	1: Touch Down, 0: Touch Off	0	X_High direction coordinate			
			$\rangle \setminus$	X_Low direction co	ordinate				
			\rightarrow	0	0	Y_High direction coordinate			
	<			Y_Low direction co	ordinate				
				Touch Pressure					
			ID9	1: Touch Down, 0: Touch Off	0	X_High direction coordinate			
				X Low direction co	⊥ ordinate				
	> \\ //			0	0	Y_High direction coordinate			
				Y_Low direction co	ordinate				
))			Touch Pressure					
0x20				The maximum X coordinate (bit 7:0)					
				The maximum X co					
				The maximum Y co		· · · · · · · · · · · · · · · · · · ·			
				The maximum Y coordinate (bit 15:8)					
				The channel numbers of X direction					
				The channel numb					
				The maximum repo					
			1	-					

			The channel numbers of TouchKey / Scrolling Bar
			For Touch Key Application
			(Maximum supports 31 Touch Key)
			Byte 8 : The Touch Key number (<32)
			Byte 9: 0xFF
0x30	Enter Sleep	Set	
	Mode		
0x40	Firmware	Get	Chin ID Code
	Version		Chip ID Code
			Major firmware version
			Minor firmware version
			Release firmware version
			For Customer Firmware Version
			For Customer Firmware Version
			For Customer Firmware Version
			For Customer Firmware Version
0x42		Get	Major protocol version : 0x03
			Minor protocol version : XX
			Release protocol version : XX

Protocol V3.X Data Format

CMD		Set									
Code	Name	1	Note	b7	b6	b 5	b4	b3	b2	b1	b0
		Get									
0x10	Touch	Get	Packet	0: No touch							\rightarrow
	Information		Number	1: Last Report at ID	0 to ID	5 (incl	ude re	lease :	status)		
				2: Last Report at ID	6 to ID	9 (incl	u de re	lease :	status)		
			ID0	1: Touch Down,	0	V Li	ah dira	otion	oordin	oto	
				0: Touch Off	0	V _U	gii uiie	CUOIT	coordin	ale	
				X_Low direction co	ordi nat e						
				0	0	Y_Hi	gh dire	ection o	coordin	ate	
				Y_Low direction co	ordinate						
				Touch Pressure							

ID1	ID1	1: Touch Down, 0: Touch Off	0	X_High direction coordinate		
		X_Low direction co	ordinat	e		
		0	0	Y_High direction coordinate		
		Y_Low direction co	ordinat	e		
		Touch Pressure				
ID2	ID2	1: Touch Down,	0	X High direction coordinate		
		0: Touch Off				
	>	X_Low direction coordinate				
		0	0	Y_High direction coordinate		
		Y_Low direction coordinate				
		Touch Pressure				
ID3		1: Touch Down,	0	Y High direction coordinate		
		0: Touch Off	U	X_High direction coordinate		
		X_Low direction co	ordinat	e		
		0	0	Y_High direction coordinate		
		Y_Low direction co	ordinat	e		
	ID4	Touch Pressure				
ID4		1: Touch Down,	0	V. High direction coordinate		
		0: Touch Off	0	X_High direction coordinate		

		X_Low direction co	ordinate				
		0	0	Y_High direction coordinate			
		Y_Low direction co	ordinate				
		Touch Pressure					
ID5	ID5	1: Touch Down,	0	V. High direction coordinate			
		0: Touch Off	O	X_High direction coordinate			
		X_Low direction co	ordinate				
		0	0	Y_High direction coordinate			
		Y_Low direction coordinate					
		Touch Pressure					

10.7 Interrupt Pin (INT) Control

Date: 2022/04/25

When a finger touches on the sensor surface, the INT pin will be pull low. TP controller supports two different type control method.



Fig 9: Method 1: INT Pin Control Diagram (Finger Touch)

Method 2(Interrupt): The INT will continue to be pull low until host read 0x10 command.

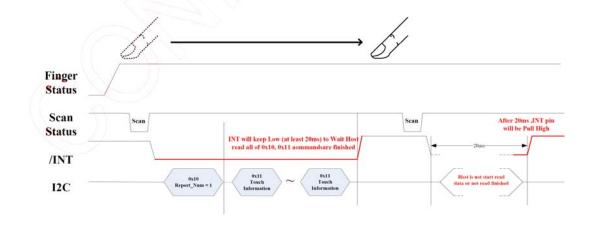


Fig 10: Method 2: INT Pin Control Diagram (Finger Touch)

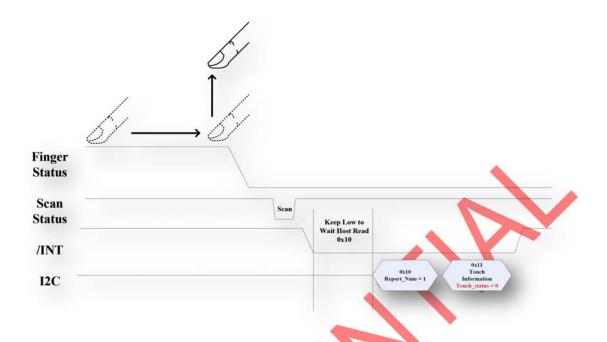
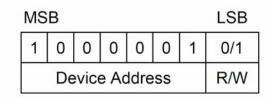


Fig 11: Method 2: INT Pin Control Diagram (Finger Release)

10.8 Device Address



7-bit Device Address: 0x41

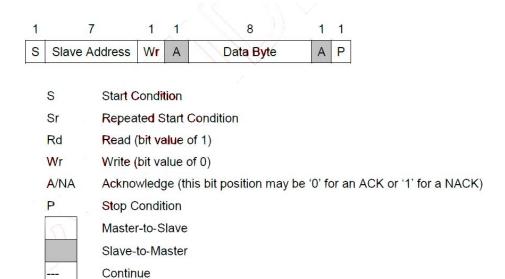
8-bit Device Read Address:0x83

8-bit Device Write Address:0x82

10.9 Data Transfer

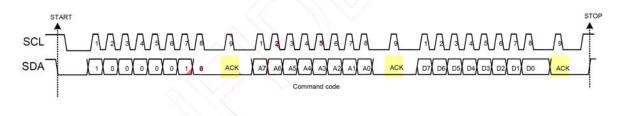
Date: 2022/04/25

Data is transferred over the IIC bus with 8-bit address and 8-bit data.



=> slave to master

Byte Write



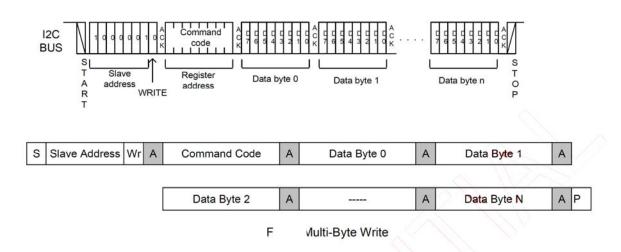
S Slave Address Wr A Command Code A Data Byte A P

F 3yte Write

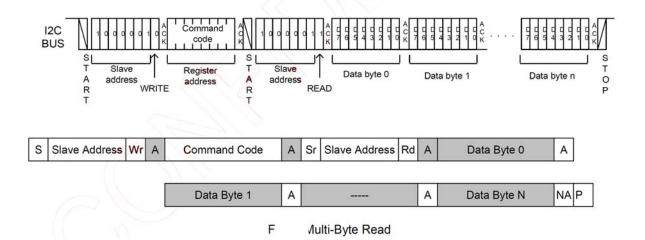
Byte Read

S Slave Address Wr A Command Code A Sr Slave Address Rd A Data Byte A P

F 3yte Read



Muiti-Byte Read



Date: 2022/04/25 AMPIRE CO., LTD.

11.0 RELIABILITY TEST CONDITIONS

Test Item	Test Conditions	Note
High Temperature Operation	70±3°C ,Dry t=240 hrs	
Low Temperature Operation	-20±3°C, Dry t=240 hrs	
High Temperature Storage	80±3°C , Dry t=240 hrs	1,2
Low Temperature Storage	-30±3°C ,Dry t=240 hrs	1,2
Thermal Shock Test	-20°C ~ 25°C ~ 70°C 30 m in. 5 min. 30 min. (1 cycle) Total 100 cycle(Dry)	1,2
Storage Humidity Test	60 °C, Humidity 90%, 240 hrs	1,2
Vibration Test (Packing)	Sweep frequency : 10 ~ 55 ~ 10 Hz/1min Amplitude : 0.75mm Test direction : X.Y.Z/3 axis Duration : 30min/each axis	2

- Note 1: Condensation of water is not permitted on the module.
- Note 2 : The module should be inspected after 1 hour storage in normal conditions (15-35°C , 45-65%RH).
- Note 3: The module shouldn't be tested more than one condition, and all the test conditions are independent.
- Note 4 : All the reliability tests should be done without protective film on the module.

Definitions of life end point:

- Current drain should be smaller than the specific value.
- Function of the module should be maintained.
- Appearance and display quality should not have degraded noticeably.
- Contrast ratio should be greater than 50% of the initial value.

12.0 USE PRECAUTIONS

12.1 Handling precautions

- 1) The polarizing plate may break easily so be careful when handling it. Do not touch, press or rub it with a hard-material tool like tweezers.
- 2) Do not touch the polarizing plate surface with bare hands so as not to make it dirty. If the surface or other related part of the polarizing plate is dirty, soak a soft cotton cloth or chamois leather in benzine and wipe off with it. Do not use chemical liquids such as acetone, toluene and isopropyl alcohol. Failure to do so may bring chemical reaction phenomena and deteriorations.
- 3) Remove any spit or water immediately. If it is left for hours, the suffered part may deform or decolorize.
- 4) If the LCD element breaks and any LC stuff leaks, do not suck or lick it. Also if LC stuff is stuck on your skin or clothing, wash thoroughly with soap and water immediately.

12.2 Installing precautions

- 1) The PCB has many ICs that may be damaged easily by static electricity. To prevent breaking by static electricity from the human body and clothing, earth the human body properly using the high resistance and discharge static electricity during the operation. In this case, however, the resistance value should be approx. $1M\Omega$ and the resistance should be placed near the human body rather than the ground surface. When the indoor space is dry, static electricity may occur easily so be careful. We recommend the indoor space should be kept with humidity of 60% or more. When a soldering iron or other similar tool is used for assembly, be sure to earth it.
- 2) When installing the module and ICs, do not bend or twist them. Failure to do so may crack LC element and cause circuit failure.
- 3) To protect LC element, especially polarizing plate, use a transparent protective plate (e.g., acrylic plate, glass etc) for the product case.
- 4) Do not use an adhesive like a both-side adhesive tape to make LCD surface (polarizing plate) and product case stick together. Failure to do so may cause the polarizing plate to peel off.

12.3 Storage precautions

- 1) Avoid a high temperature and humidity area. Keep the temperature between 0°C and 35°C and also the humidity under 60%.
- 2) Choose the dark spaces where the product is not exposed to direct sunlight or fluorescent light.
- 3) Store the products as they are put in the boxes provided from us or in the same conditions as we recommend.

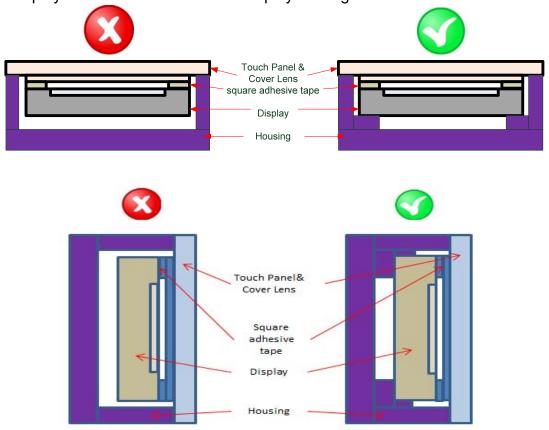
12.4 Operating precautions

- 1) Do not boost the applied drive voltage abnormally. Failure to do so may break ICs. When applying power voltage, check the electrical features beforehand and be careful. Always turn off the power to the LC module controller before removing or inserting the LC module input connector. If the input connector is removed or inserted while the power is turned on, the LC module internal circuit may break.
- 2) The display response may be late if the operating temperature is under the normal standard, and the display may be out of order if it is above the normal standard. But this is not a failure; this will be restored if it is within the normal standard.
- The LCD contrast varies depending on the visual angle, ambient temperature, power voltage etc. Obtain the optimum contrast by adjusting the LC dive voltage.
- 4) When carrying out the test, do not take the module out of the low-temperature space suddenly. Failure to do so will cause the module condensing, leading to malfunctions.
- 5) Make certain that each signal noise level is within the standard (L level: 0.2Vdd or less and H level: 0.8Vdd or more) even if the module has functioned properly. If it is beyond the standard, the module may often malfunction. In addition, always connect the module when making noise level measurements.
- 6) The CMOS ICs are incorporated in the module and the pull-up and pull-down function is not adopted for the input so avoid putting the input signal open while the power is ON.
- 7) The characteristic of the semiconductor element changes when it is exposed to light emissions, therefore ICs on the LCD may malfunction if they receive light emissions. To prevent these malfunctions, design and assemble ICs so that they are shielded from light emissions.

8) Crosstalk occurs because of characteristics of the LCD. In general, crosstalk occurs when the regularized display is maintained. Also, crosstalk is affected by the LC drive voltage. Design the contents of the display, considering crosstalk.

12.5 Mechanism

- (1) Please mount LCD module by using mounting holes arranged in four corners tightly.
- (2) The square adhesive tape which is between the touch panel and display can't provide well supporting in the long term and high ambient temperature condition. Whether upright or horizontal position the support holder which is in the back side of the display is needed. Do not let the display floating.



12.6 Other

- 1) Do not disassemble or take the LC module into pieces. The LC modules once disassembled or taken into pieces are not the guarantee articles.
- 2) Do not keep the LCD at the same display pattern continually. The residual image will happen and it will damage the LCD. Please use screen saver.
- 3) AMIPRE will provide one year warrantee for all products and three months warrantee for all repairing products.

13.0 MECHANIC DRAWING

